

## Specification document of BD1020HFV

Component manufacturer	ROHM Semiconductor
Model number	BD1020HFV
Datasheets	<a href="#">BD1020HFV : Sensors &amp; MEMS (rohm.com)</a>
Specification Ver	01.00.00      Oct 20,2022      New release
Documentation provided	Rui Long Lab Inc. <a href="https://rui-long-lab.com/">https://rui-long-lab.com/</a>

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## 1. Component datasheet

Temperature accuracy	$\pm 1.5^\circ \text{ C} (\text{Max}) @ T_a = 30^\circ \text{ C}$
	$\pm 2.5^\circ \text{ C} (\text{Max}) @ T_a = -30^\circ \text{ C}, +100^\circ \text{ C}$
Temperature range	-30 to $+100^\circ \text{ C}$
Range of power supply voltage ( Vdd )	2.4 to 5.5[V]
Output voltage ( Vout )	Linear $-8.2 [\text{mV}/^\circ \text{ C}] \text{ Typ.}$ $30 [^\circ \text{ C}] 1.3 [\text{V}] \text{ Typ.}$
Calculation	$V_{\text{out}} = 1.3\text{V} + (-0.0082 \text{ V}/^\circ \text{ C} \times (T_a - 30^\circ \text{ C}))$ $T_a = (V_{\text{out}} - 1.3\text{V}) / (-0.0082 \text{ V}/^\circ \text{ C}) + 30^\circ \text{ C}$
Vdd vs Vout	Non-link

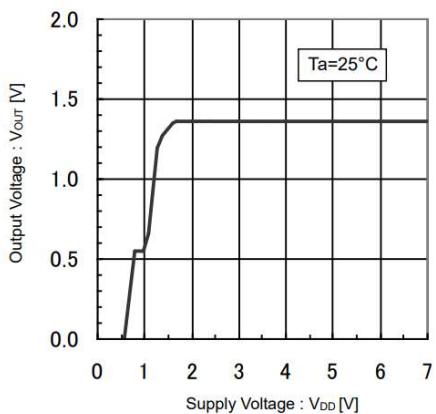


Figure 3. Output Voltage vs Supply Voltage

## Applications

### IoT etc

- Cell Phone ( RF Module, Battery Thermal Management )
- Audio Systems
- Digital Still Camera, LCD, PDP
- Optical pick up module for DVD and BlueRay

## 2. Component Software IF specification

The software interface specifications based on the BD1020HFV component specifications are as follows.

The voltage value-to-physical value conversion equation is a linear conversion equation as shown in the equation below.

ADC value to voltage value conversion formula

$$vi = ( ai \times iADC_vdd ) / 2^{iADC\_bit} [V]$$

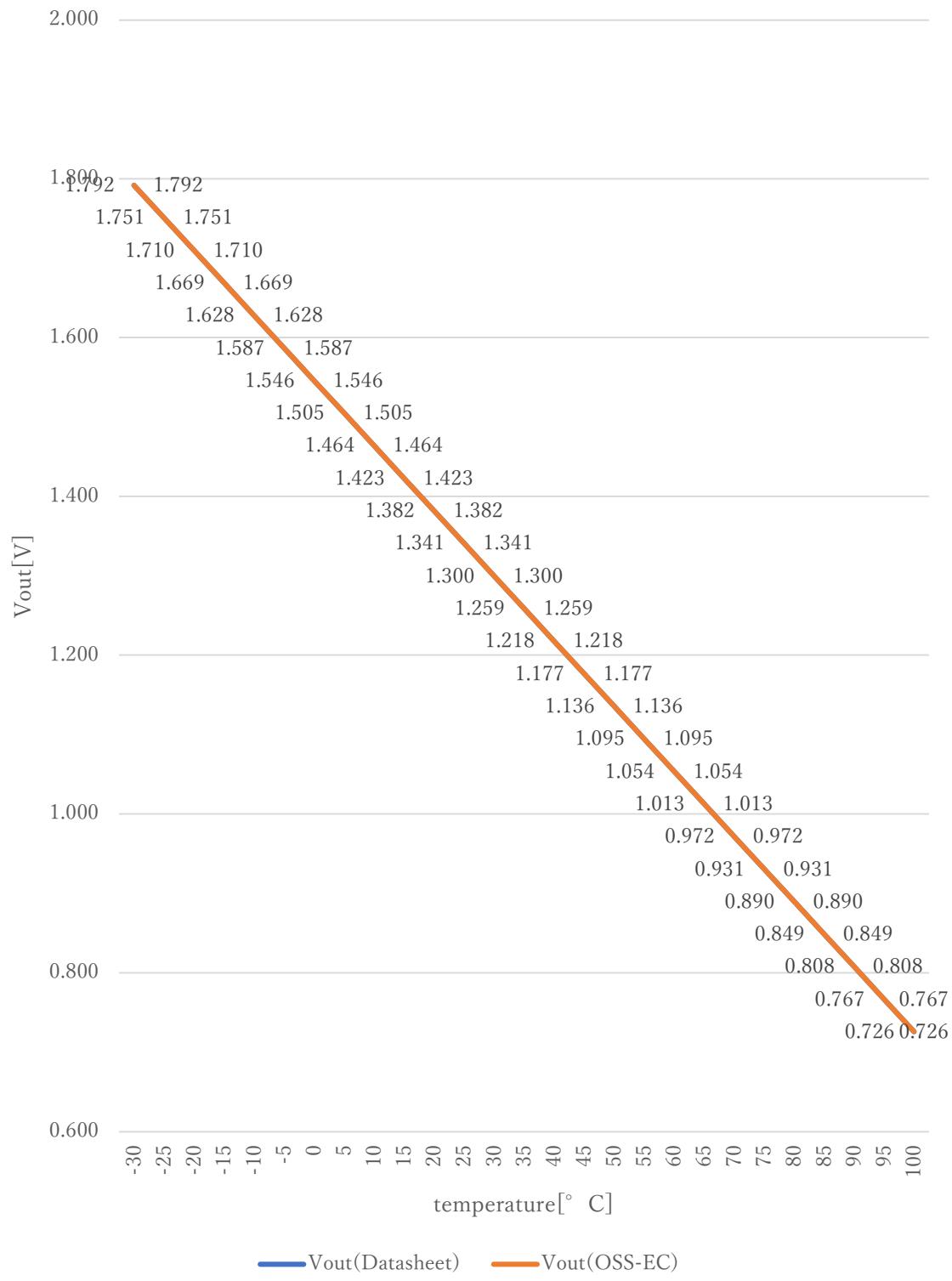
Voltage value to physical value conversion formula

$$y = ( vi - iBD1020HFV_xoff ) / iBD1020HFV_gain + iBD1020HFV_yoff [^{\circ}C]$$

$$iBD1020HFV_{min} \leqq y \leqq iBD1020HFV_{max}$$

ai	A/D conversion value
vi	Sensor output voltage value [V]
iADC_vdd	Sensor supply voltage value [V]
iADC_bit	A/D conversion bit length
y	Temperature value [^{\circ}C]
#define iBD1020HFV_xoff	<u>1.3F</u> // X offset [V]
#define iBD1020HFV_yoff	<u>30.0F</u> // Y offset [^{\circ}C]
#define iBD1020HFV_gain	<u>-0.0082F</u> // Gain [V/^{\circ}C]
#define iBD1020HFV_max	<u>100.0F</u> // Temperature Max [^{\circ}C]
#define iBD1020HFV_min	<u>-30.0F</u> // Temperature Min [^{\circ}C]

## Datasheet : OSS-EC



### 3. File Structure and Definitions

BD1020HFV.h

```
#include "user_define.h"

// Components number
#define iBD1020HFV      122U                         // ROHM BD1020HFV

// BD1020HFV System Parts definitions
#define iBD1020HFV_xoff    1.3F                      // X offset [V]
#define iBD1020HFV_yoff    30.0F                     // Y offset [°C]
#define iBD1020HFV_gain    -0.0082F                // Gain [V/°C]
#define iBD1020HFV_max     100.0F                   // Temperature Max [°C]
#define iBD1020HFV_min     -30.0F                   // Temperature Min [°C]

extern const tbl_adc_t tbl_BD1020HFV;
```

## BD1020HFV.cpp

```
#include      "BD1020HFV.h"

#if      iBD1020HFV_ma == iSMA                         // Simple moving average filter
static float32 BD1020HFV_sma_buf[iBD1020HFV_SMA_num];
static const sma_f32_t BD1020HFV_Phy_SMA =
{
    iInitial ,                                         // Initial state
    iBD1020HFV_SMA_num ,                            // Simple moving average number & buf size
    0U ,                                              // buffer position
    0.0F ,                                            // sum
    &BD1020HFV_sma_buf[0]                           // buffer
};

#elif    iBD1020HFV_ma == iEMA                         // Exponential moving average filter
static const ema_f32_t BD1020HFV_Phy_EMA =
{
    iInitial ,                                         // Initial state
    0.0F ,                                            // Xn-1
    iBD1020HFV_EMA_K                                // Exponential smoothing factor
};

#elif    iBD1020HFV_ma == iWMA                         // Weighted moving average filter
static float32 BD1020HFV_wma_buf[iBD1020HFV_WMA_num];
static const wma_f32_t BD1020HFV_Phy_WMA =
{
    iInitial ,                                         // Initial state
    iBD1020HFV_WMA_num ,                            // Weighted moving average number & buf size
    0U ,                                              // buffer poition
    iBD1020HFV_WMA_num * (iBD1020HFV_WMA_num + 1)/2 , // kn sum
    &BD1020HFV_wma_buf[0]                           // Xn buffer
};

#else
#endif

#define iDummy_adr        0xffffffff                 // Dummy address
```

```

const tbl_adc_t tbl_BD1020HFV =
{
    iBD1020HFV        ,
    iBD1020HFV_pin    ,
    iBD1020HFV_xoff   ,
    iBD1020HFV_yoff   ,
    iBD1020HFV_gain   ,
    iBD1020HFV_max    ,
    iBD1020HFV_min    ,
    iBD1020HFV_ma     ,

#if      iBD1020HFV_ma == iSMA           // Simple moving average filter
&BD1020HFV_Phy_SMA    ,
(ema_f32_t*) iDummy_adr ,
(wma_f32_t*) iDummy_adr

#elif    iBD1020HFV_ma == iEMA           // Exponential moving average filter
(sma_f32_t*) iDummy_adr ,
&BD1020HFV_Phy_EMA    ,
(wma_f32_t*) iDummy_adr

#elif    iBD1020HFV_ma == iWMA           // Weighted moving average filter
(sma_f32_t*) iDummy_adr ,
(ema_f32_t*) iDummy_adr ,
(wma_f32_t*) iDummy_adr
&BD1020HFV_Phy_WMA

#else                           // Non-moving average filter
(sma_f32_t*) iDummy_adr ,
(ema_f32_t*) iDummy_adr ,
(wma_f32_t*) iDummy_adr

#endif

};


```