



Specification document of TC1047, TC1047A

Component manufacturer	Microchip Technology		
Model number	TC1047, TC1047A		
Datasheets	21498D.book (microchip.com)		
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1. Component datasheet	2
2. Component Software IF specification	3
3. File Structure and Definitions	5

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1. Component datasheet

Temperature accuracy	$\pm 2.0^{\circ} \text{ C}$ (Max at $+25^{\circ} \text{ C}$)
Temperature range	-40 to $+125^{\circ} \text{ C}$
Range of power supply voltage (Vdd)	2.7 to 4.4 [V] TC1047 2.5 to 5.5 [V] TC1047A
Output voltage (Vout)	Linear $0.01 [\text{mV}/^{\circ} \text{ C}]$ Typ. $0 [^{\circ} \text{ C}]$ $0.5 [\text{V}]$ Typ.
Calculation	$\text{Vout} = 0.5\text{V} + (0.01 \text{ V}/^{\circ} \text{ C} \times \text{Ta})$ $\text{Ta} = (\text{Vout} - 0.5\text{V}) / (0.01 \text{ V}/^{\circ} \text{ C})$

Applications

IoT etc

- Cellular Phones
- Power Supply Thermal Shutdown
- Temperature-Controlled Fans
- Temperature Measurement/Instrumentation
- Temperature Regulators
- Consumer Electronics
- Portable Battery-Powered Equipment

2. Component Software IF specification

The software interface specifications based on the TC1047, TC1047A component specifications are as follows.

The voltage value-to-physical value conversion equation is a linear conversion equation as shown in the equation below.

ADC value to voltage value conversion formula

$$v_i = (a_i \times i_{ADC_vdd}) / 2^{i_{ADC_bit}} \quad [V]$$

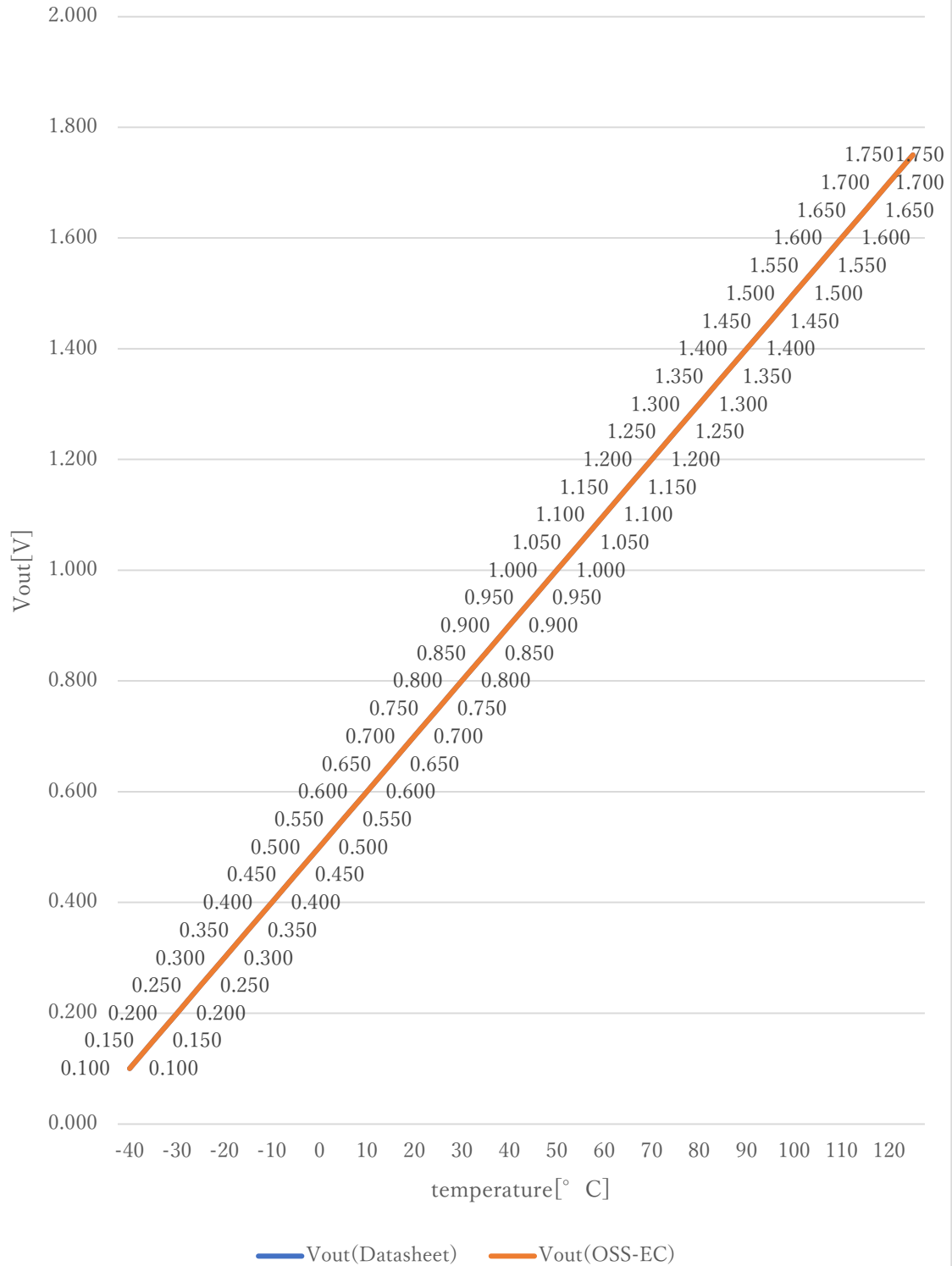
Voltage value to physical value conversion formula

$$y = (v_i - i_{TC1047_xoff}) / i_{TC1047_gain} + i_{TC1047_yoff} \quad [^{\circ}C]$$

$$i_{TC1047_min} \leq y \leq i_{TC1047_max}$$

a_i	A/D conversion value	
v_i	Sensor output voltage value [V]	
i_{ADC_vdd}	Sensor supply voltage value [V]	
i_{ADC_bit}	A/D conversion bit length	
y	Temperature value [$^{\circ}C$]	
<code>#define iTC1047_xoff</code>	<u>0.5F</u>	// X offset [V]
<code>#define iTC1047_yoff</code>	<u>0.0F</u>	// Y offset [$^{\circ}C$]
<code>#define iTC1047_gain</code>	<u>0.01F</u>	// Gain [V/ $^{\circ}C$]
<code>#define iTC1047_max</code>	<u>125.0F</u>	// Temperature Max [$^{\circ}C$]
<code>#define iTC1047_min</code>	<u>-40.0F</u>	// Temperature Min [$^{\circ}C$]

Datasheet : OSS-EC



3. File Structure and Definitions

TC1047.h

```
#include "user_define.h"

// Components number
#define iTC1047          117U          // Microchip Technology TC1047, TC1047A

// TC1047 System Parts definitions
#define iTC1047_xoff      0.5F      // X offset [V]
#define iTC1047_yoff      0.0F      // Y offset [°C]
#define iTC1047_gain      0.01F     // Gain [V/°C]
#define iTC1047_max        125.0F    // Temperature Max [°C]
#define iTC1047_min        -40.0F    // Temperature Min [°C]

extern const tbl_adc_t tbl_TC1047;
```

TC1047.cpp

```
#include "TC1047.h"

#if iTC1047_ma == iSMA // Simple moving average filter
static float32 TC1047_sma_buf[iTC1047_SMA_num];
static const sma_f32_t TC1047_Phy_SMA =
{
    iInitial , // Initial state
    iTC1047_SMA_num , // Simple moving average number & buf size
    0U , // buffer position
    0.0F , // sum
    &TC1047_sma_buf[0] // buffer
};

#elif iTC1047_ma == iEMA // Exponential moving average filter
static const ema_f32_t TC1047_Phy_EMA =
{
    iInitial , // Initial state
    0.0F , // Xn-1
    iTC1047_EMA_K // Exponential smoothing factor
};

#elif iTC1047_ma == iWMA // Weighted moving average filter
static float32 TC1047_wma_buf[iTC1047_WMA_num];
static const wma_f32_t TC1047_Phy_WMA =
{
    iInitial , // Initial state
    iTC1047_WMA_num , // Weighted moving average number & buf size
    0U , // buffer position
    iTC1047_WMA_num * (iTC1047_WMA_num + 1)/2 , // kn sum
    &TC1047_wma_buf[0] // Xn buffer
};

#else // Non-moving average filter
#endif

#define iDummy_adr 0xffffffff // Dummy address
```

```
const tbl_adc_t tbl_TC1047 =
{
    iTC1047          ,
    iTC1047_pin      ,
    iTC1047_xoff     ,
    iTC1047_yoff     ,
    iTC1047_gain     ,
    iTC1047_max      ,
    iTC1047_min      ,
    iTC1047_ma       ,

    #if iTC1047_ma == iSMA // Simple moving average filter
        &TC1047_Phy_SMA ,
        (ema_f32_t*) iDummy_adr ,
        (wma_f32_t*) iDummy_adr
    #elif iTC1047_ma == iEMA // Exponential moving average filter
        (sma_f32_t*) iDummy_adr ,
        &TC1047_Phy_EMA ,
        (wma_f32_t*) iDummy_adr
    #elif iTC1047_ma == iWMA // Weighted moving average filter
        (sma_f32_t*) iDummy_adr ,
        (ema_f32_t*) iDummy_adr ,
        &TC1047_Phy_WMA
    #else // Non-moving average filter
        (sma_f32_t*) iDummy_adr ,
        (ema_f32_t*) iDummy_adr ,
        (wma_f32_t*) iDummy_adr
    #endif

};
```