



## Specification document of AD22100A

Component manufacturer	Analog Devices		
Model number	AD22100A		
Datasheets	<a href="#">AD22100 (REV. D) (analog.com)</a>		
Specification Ver	01.00.00	Oct 03,2022	New release
Documentation provided	Rui Long Lab Inc. <a href="https://rui-long-lab.com/">https://rui-long-lab.com/</a>		

1. Component datasheet .....	2
2. Component Software IF specification .....	3
3. File Structure and Definitions .....	5

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## 1. Component datasheet

Temperature accuracy	$\pm 2.0^{\circ}\text{C}$ ( $-40^{\circ}\text{C}$ to $+85^{\circ}\text{C}$ )
Range of power supply voltage ( Vdd )	4.0 to 6.5[V]
Output voltage ( Vout )	Linear $22.5 \times \text{Vdd}/5$ [mV/ $^{\circ}\text{C}$ ] Typ. Vdd = 5.0 [V] -40 [ $^{\circ}\text{C}$ ] 0.475[V] Typ. 85 [ $^{\circ}\text{C}$ ] 3.288 [V] Typ.
Calculation	$\text{Vout} = (\text{Vdd}/5\text{ V}) \times (1.375\text{ V} + 22.5\text{ mV}/^{\circ}\text{C} \times \text{Ta})$ $\text{Ta} = (\text{Vout} / (\text{Vdd}/5\text{V}) - 1.375\text{V}) / 22.5\text{ mV}/^{\circ}\text{C}$

## 2. Component Software IF specification

The software interface specifications based on the AD22100A component specifications are as follows.

The voltage value-to-physical value conversion equation is a linear conversion equation as shown in the equation below.

ADC value to voltage value conversion formula

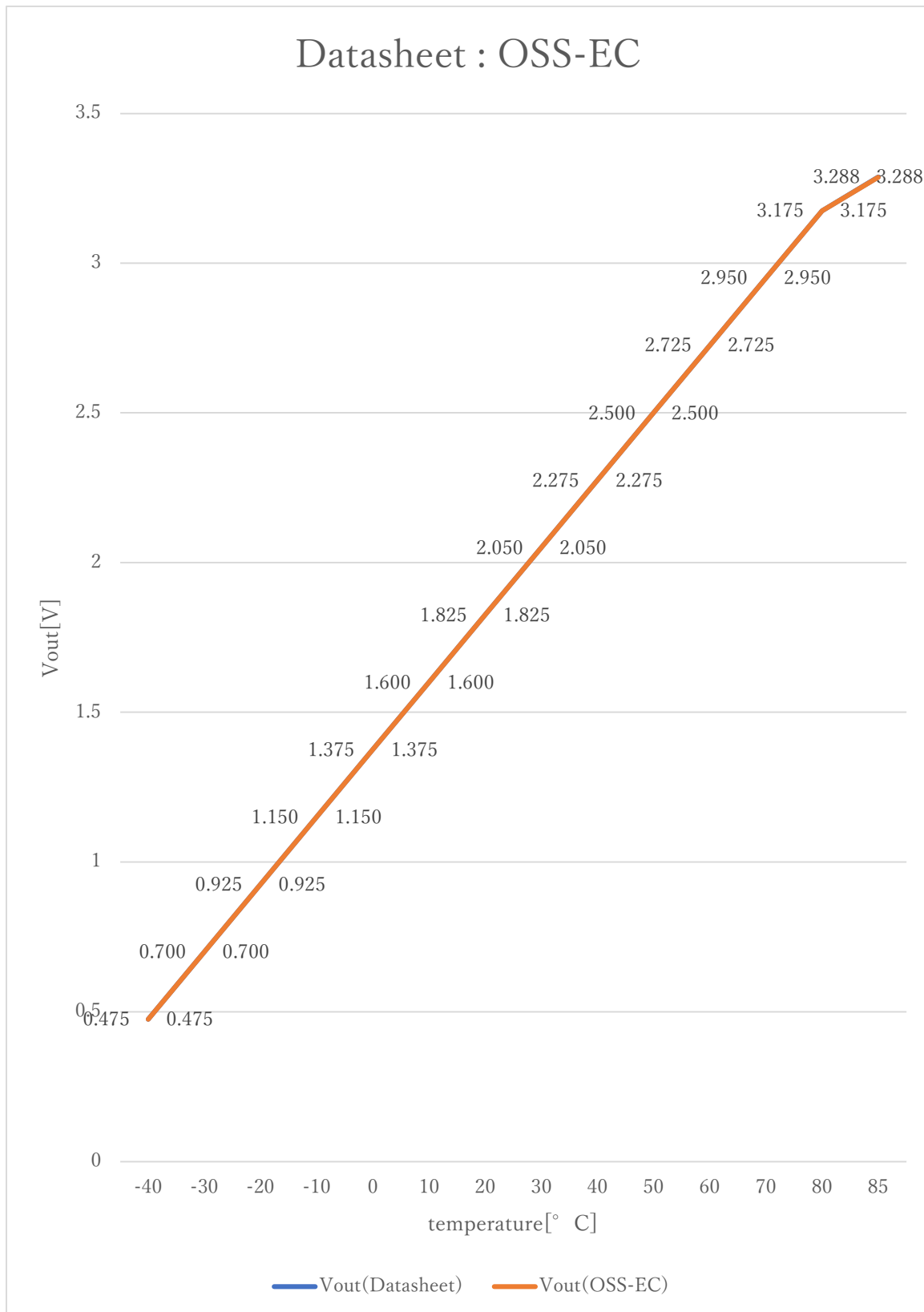
$$v_i = ( a_i \times i_{ADC\_vdd} ) / 2^{i_{ADC\_bit}} \quad [V]$$

Voltage value to physical value conversion formula

$$y = ( v_i - i_{AD22100A\_xoff} ) / i_{AD22100A\_gain} + i_{AD22100A\_yoff} \quad [^{\circ}C]$$

$$i_{AD22100A\_min} \leq y \leq i_{AD22100A\_max}$$

$a_i$	A/D conversion value
$v_i$	Sensor output voltage value [V]
$i_{ADC\_vdd}$	Sensor supply voltage value [V]
$i_{ADC\_bit}$	A/D conversion bit length
$y$	Temperature value [ $^{\circ}C$ ]
<code>#define iAD22100A_xoff</code>	<code>(1.375F*(iADC_vdd/5.0))</code> // X offset [V]
<code>#define iAD22100A_yoff</code>	<code>0.0F</code> // Y offset [ $^{\circ}C$ ]
<code>#define iAD22100A_gain</code>	<code>(0.0225F*(iADC_vdd/5.0))</code> // Gain [V/ $^{\circ}C$ ]
<code>#define iAD22100A_max</code>	<code>85.0F</code> // Temperature Max [ $^{\circ}C$ ]
<code>#define iAD22100A_min</code>	<code>-40.0F</code> // Temperature Min [ $^{\circ}C$ ]



### 3. File Structure and Definitions

#### AD22100A.h

```
#include "user_define.h"

// Components number
#define iAD22100A          106U          // Analog devices AD22100A

// AD22100A System Parts definitions
#define iAD22100A_xoff      (1.375F*(iADC_vdd/5.0)) // X offset [V]
#define iAD22100A_yoff      0.0F                // Y offset [°C]
#define iAD22100A_gain      (0.0225F*(iADC_vdd/5.0)) // Gain [V/°C]
#define iAD22100A_max        85.0F                // Temperature Max [°C]
#define iAD22100A_min        -40.0F                // Temperature Min [°C]

extern const tbl_adc_t tbl_AD22100A;
```

## AD22100A.cpp

```
#include      "AD22100A.h"

#if      iAD22100A_ma == iSMA                // Simple moving average filter
static float32 AD22100A_sma_buf[iAD22100A_SMA_num];
static const sma_f32_t AD22100A_Phy_SMA =
{
    iInitial ,                                // Initial state
    iAD22100A_SMA_num ,                      // Simple moving average number & buf
size
    OU ,                                     // buffer position
    0.0F ,                                   // sum
    &AD22100A_sma_buf[0]                    // buffer
};

#elif      iAD22100A_ma == iEMA                // Exponential moving average filter
static const ema_f32_t AD22100A_Phy_EMA =
{
    iInitial ,                                // Initial state
    0.0F ,                                   // Xn-1
    iAD22100A_EMA_K                          // Exponential smoothing factor
};

#elif      iAD22100A_ma == iWMA                // Weighted moving average filter
static float32 AD22100A_wma_buf[iAD22100A_WMA_num];
static const wma_f32_t AD22100A_Phy_WMA =
{
    iInitial ,                                // Initial state
    iAD22100A_WMA_num ,                      // Weighted moving average number & buf size
    OU ,                                     // buffer poition
    iAD22100A_WMA_num * (iAD22100A_WMA_num + 1)/2 , // kn sum
    &AD22100A_wma_buf[0]                    // Xn buffer
};

#else                                          // Non-moving average filter
#endif

#define iDummy_adr      0xffffffff          // Dummy address

const tbl_adc_t tbl_AD22100A =
```

```

{
    iAD22100A          ,
    iAD22100A_pin      ,
    iAD22100A_xoff     ,
    iAD22100A_yoff     ,
    iAD22100A_gain     ,
    iAD22100A_max      ,
    iAD22100A_min      ,
    iAD22100A_ma       ,

    #if iAD22100A_ma == iSMA // Simple moving average filter
        &AD22100A_Phy_SMA ,
        (ema_f32_t*) iDummy_adr ,
        (wma_f32_t*) iDummy_adr
    #elif iAD22100A_ma == iEMA // Exponential moving average filter
        (sma_f32_t*) iDummy_adr ,
        &AD22100A_Phy_EMA ,
        (wma_f32_t*) iDummy_adr
    #elif iAD22100A_ma == iWMA // Weighted moving average filter
        (sma_f32_t*) iDummy_adr ,
        (ema_f32_t*) iDummy_adr ,
        &AD22100A_Phy_WMA
    #else // Non-moving average filter
        (sma_f32_t*) iDummy_adr ,
        (ema_f32_t*) iDummy_adr ,
        (wma_f32_t*) iDummy_adr
    #endif

};

```